

# Learning Quadratic Games on Networks

Xiaowen Dong

Department of Engineering Science

University of Oxford

(joint work with Yan Leng, Junfeng Wu, and Alex Pentland)

University of Bath, July 2020



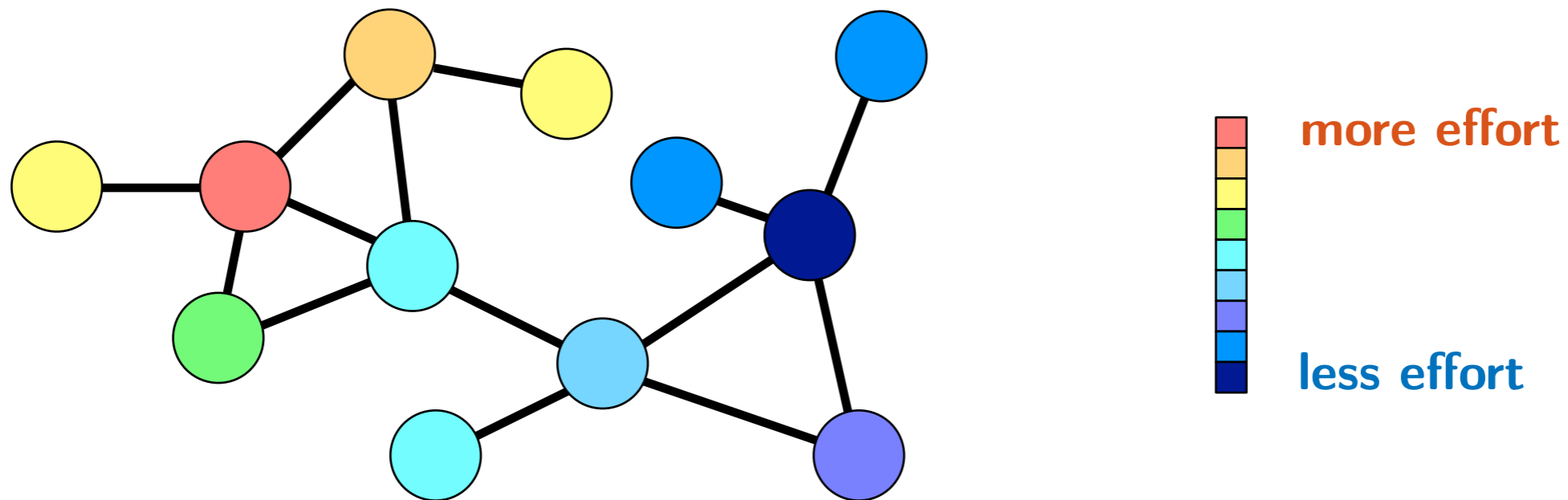
# Motivation

- Consider a group of students making choices on educational effort
  - making effort is costly
  - I will benefit from my own effort
  - I will also benefit from my friends' effort

# Motivation

- Consider a group of students making choices on educational effort
  - making effort is costly
  - I will benefit from my own effort
  - I will also benefit from my friends' effort

 **tend to make effort if friends do**



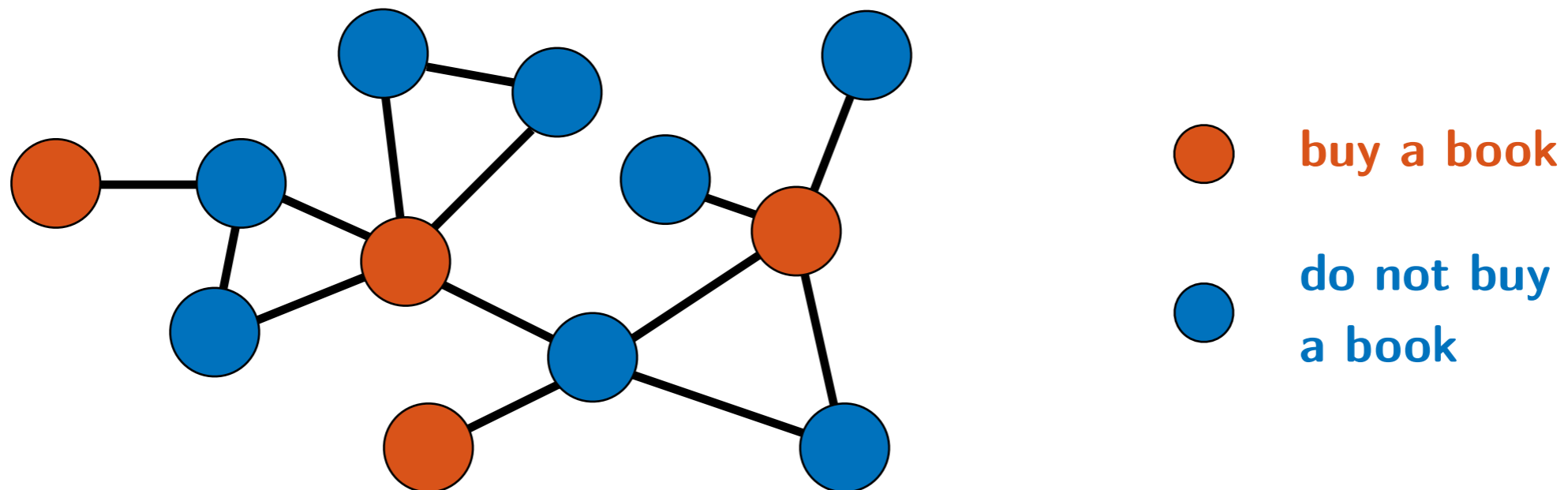
# Motivation

- Consider a group of students making choices on buying a book
  - buying a book is costly
  - if a friend of mine will buy, then I will not buy
  - but if none of my friends will buy, then I will buy

# Motivation

- Consider a group of students making choices on buying a book
  - buying a book is costly
  - if a friend of mine will buy, then I will not buy
  - but if none of my friends will buy, then I will buy

 **tend not to make effort if friends do**



# Motivation

- Such strategic interactions can be modelled as games on networks
  - players, actions, payoffs, **interaction network**



# Motivation

- Such strategic interactions can be modelled as games on networks
  - players, actions, payoffs, **interaction network**
  - payoff of an individual depends on **her action** as well as **her neighbours' actions**



# Motivation

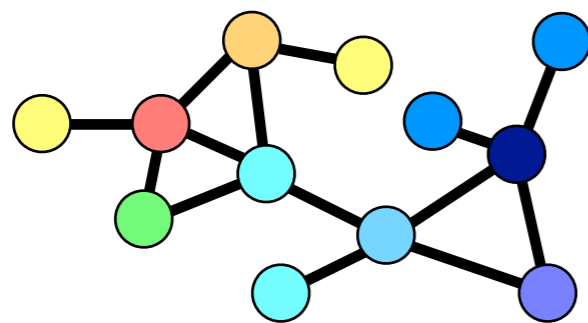
- Such strategic interactions can be modelled as games on networks
  - players, actions, payoffs, **interaction network**
  - payoff of an individual depends on **her action** as well as **her neighbours' actions**
  - strategic **complements** or strategic **substitutes**



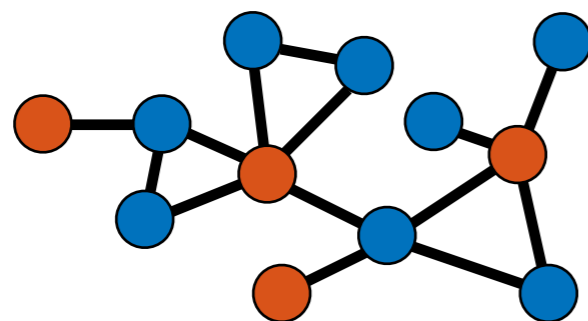


# Motivation

- Such strategic interactions can be modelled as games on networks
  - players, actions, payoffs, **interaction network**
  - payoff of an individual depends on **her action** as well as **her neighbours' actions**
  - strategic **complements** or strategic **substitutes**



more effort  
less effort



buy a book  
do not buy a book



# Motivation

- Economics
  - existence of equilibrium or how action/payoff depends on network structure
  - on a **given or predefined** network



# Motivation

- Economics
  - existence of equilibrium or how action/payoff depends on network structure
  - on a **given or predefined** network
- Computer science (graphical games)
  - algorithms for computing equilibrium
  - **binary or finite discrete** action space



# Motivation

- Economics
  - existence of equilibrium or how action/payoff depends on network structure
  - on a **given or predefined** network
- Computer science (graphical games)
  - algorithms for computing equilibrium
  - **binary or finite discrete** action space
- This work
  - **learning network** given **continuous actions**



# Motivation

- Economics
  - existence of equilibrium or how action/payoff depends on network structure
  - on a **given or predefined** network
- Computer science (graphical games)
  - algorithms for computing equilibrium
  - **binary or finite discrete** action space
- This work
  - **learning network** given **continuous actions**
- Many examples
  - observe individual decisions (e.g., adoptions), but not social relationship
  - observe R&D activities of firms, but not collaboration networks
  - observe international policies of countries, but not political alliance



# Outline

- Background
  - learning network structure from data
  - network games with linear-quadratic payoffs
- Learning games with linear-quadratic payoffs
  - independent marginal benefits
  - homophilous marginal benefits
- Experimental results
- Discussion

# Outline

- Background
  - learning network structure from data
  - network games with linear-quadratic payoffs
- Learning games with linear-quadratic payoffs
  - independent marginal benefits
  - homophilous marginal benefits
- Experimental results
- Discussion

# Learning network structure from data

- Different perspectives in the literature
  - statistical: graph captures **data distribution** (e.g., probabilistic graphical model)
  - physics: data correspond to **physical process** on graph (e.g., network cascade)
  - signal processing: graph enforces **signal property** (e.g., smoothness)



# Learning network structure from data

- Different perspectives in the literature
  - statistical: graph captures **data distribution** (e.g., probabilistic graphical model)
  - physics: data correspond to **physical process** on graph (e.g., network cascade)
  - signal processing: graph enforces **signal property** (e.g., smoothness)
- **No game-theoretic aspect** of strategic interactions

# Network games with linear-quadratic payoffs

- Consider a graph  $\mathcal{G} = \{\mathcal{V}, \mathcal{E}\}$  with edge weights  $G_{ij}$

# Network games with linear-quadratic payoffs

- Consider a graph  $\mathcal{G} = \{\mathcal{V}, \mathcal{E}\}$  with edge weights  $G_{ij}$
- Payoff of player  $i$ :  $u_i(a_i, \{a_j\}_{j \in \mathcal{N}(i)}, G_{ij})$

# Network games with linear-quadratic payoffs


- Consider a graph  $\mathcal{G} = \{\mathcal{V}, \mathcal{E}\}$  with edge weights  $G_{ij}$
- Payoff of player  $i$ :  $u_i(a_i, \{a_j\}_{j \in \mathcal{N}(i)}, G_{ij})$
- Games with linear-quadratic payoffs

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{N}(i)} G_{ij} a_j$$

# Network games with linear-quadratic payoffs

- Consider a graph  $\mathcal{G} = \{\mathcal{V}, \mathcal{E}\}$  with edge weights  $G_{ij}$
- Payoff of player  $i$ :  $u_i(a_i, \{a_j\}_{j \in \mathcal{N}(i)}, G_{ij})$
- Games with linear-quadratic payoffs

**individual action**

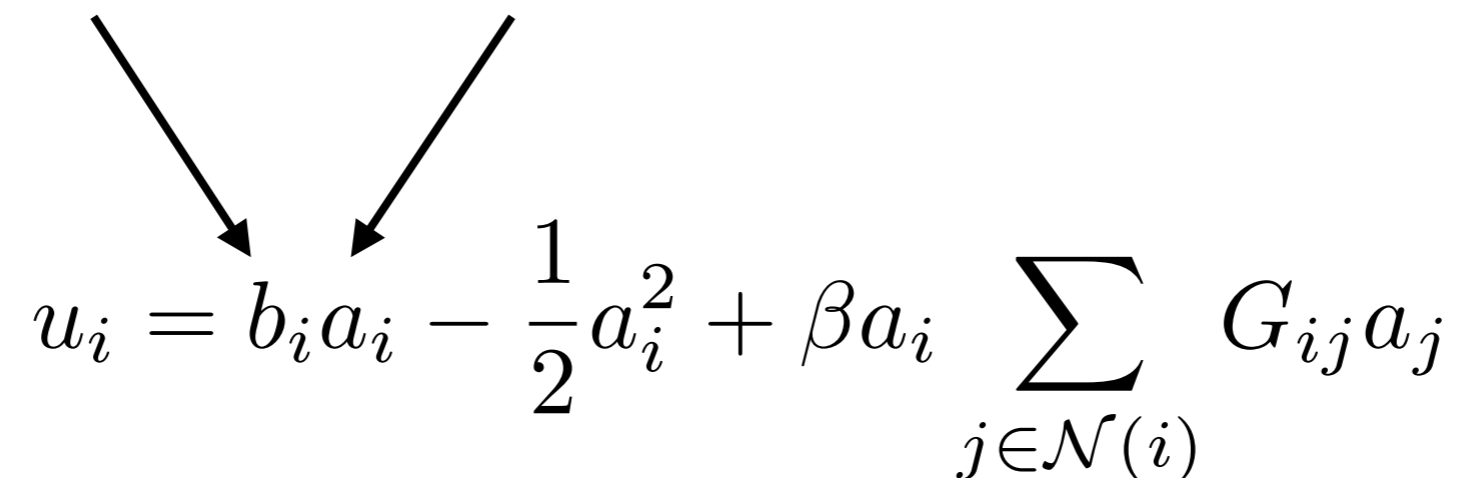

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{N}(i)} G_{ij} a_j$$

# Network games with linear-quadratic payoffs

- Consider a graph  $\mathcal{G} = \{\mathcal{V}, \mathcal{E}\}$  with edge weights  $G_{ij}$
- Payoff of player  $i$ :  $u_i(a_i, \{a_j\}_{j \in \mathcal{N}(i)}, G_{ij})$
- Games with linear-quadratic payoffs

marginal benefit

individual action


$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{N}(i)} G_{ij} a_j$$

# Network games with linear-quadratic payoffs

- Consider a graph  $\mathcal{G} = \{\mathcal{V}, \mathcal{E}\}$  with edge weights  $G_{ij}$
- Payoff of player  $i$ :  $u_i(a_i, \{a_j\}_{j \in \mathcal{N}(i)}, G_{ij})$
- Games with linear-quadratic payoffs

**marginal benefit**      **individual action**      **network factor**

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{N}(i)} G_{ij} a_j$$

# Network games with linear-quadratic payoffs

- Consider a graph  $\mathcal{G} = \{\mathcal{V}, \mathcal{E}\}$  with edge weights  $G_{ij}$
- Payoff of player  $i$ :  $u_i(a_i, \{a_j\}_{j \in \mathcal{N}(i)}, G_{ij})$
- Games with linear-quadratic payoffs

The diagram shows the payoff function  $u_i$  for player  $i$  in a network game. The function is split into two parts, each enclosed in a light blue oval. The first part,  $b_i a_i - \frac{1}{2} a_i^2$ , is labeled "individual effect" in orange text below it. The second part,  $\beta a_i \sum_{j \in \mathcal{N}(i)} G_{ij} a_j$ , is labeled "network effect" in orange text below it. Three blue labels with arrows point to specific parts of the equation: "marginal benefit" points to  $b_i a_i$ , "individual action" points to  $a_i$ , and "network factor" points to the summation term  $\sum_{j \in \mathcal{N}(i)} G_{ij} a_j$ .

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{N}(i)} G_{ij} a_j$$

**marginal benefit**      **individual action**      **network factor**

**individual effect**      **network effect**



# Network games with linear-quadratic payoffs

marginal benefit      individual action      network factor

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{N}(i)} G_{ij} a_j$$

individual effect      network effect

## remarks

- continuous actions
- for strategic complements ( $\beta > 0$ ) and substitutes ( $\beta < 0$ )
- can be used to approximate complex non-linear payoffs
- widely adopted in literature [Jackson15, Bramoullé16]

# Network games with linear-quadratic payoffs

marginal benefit      individual action      network factor

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{N}(i)} G_{ij} a_j$$

individual effect      network effect

## remarks

- continuous actions
- for strategic complements ( $\beta > 0$ ) and substitutes ( $\beta < 0$ )
- can be used to approximate complex non-linear payoffs
- widely adopted in literature [Jackson15, Bramoullé16]

## examples

- education: action is educational effort, utility is achievement
- collaboration: action is joint R&D activities, utility is firm profit
- urban dynamics: action is mobility behaviour, utility is convenience/satisfaction

# Network games with linear-quadratic payoffs

- Pure-strategy Nash equilibrium (PSNE)

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{V}} G_{ij} a_j$$

# Network games with linear-quadratic payoffs

- Pure-strategy Nash equilibrium (PSNE)

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{V}} G_{ij} a_j \quad \longrightarrow \quad \frac{\partial u_i}{\partial a_i} = b_i - a_i + \beta (\mathbf{G}\mathbf{a})_i$$

$$\longrightarrow \quad \mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b}$$

# Network games with linear-quadratic payoffs

- Pure-strategy Nash equilibrium (PSNE)

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{V}} G_{ij} a_j \quad \longrightarrow \quad \frac{\partial u_i}{\partial a_i} = b_i - a_i + \beta (\mathbf{G}\mathbf{a})_i$$

$$\longrightarrow \quad \mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b}$$

**assumption:** spectral radius  $\rho(\beta \mathbf{G})$  is smaller than 1

- guarantees matrix inversion
- ensures uniqueness and stability of equilibrium action [Ballester06]

# Network games with linear-quadratic payoffs

- Pure-strategy Nash equilibrium (PSNE)

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{V}} G_{ij} a_j \quad \longrightarrow \quad \frac{\partial u_i}{\partial a_i} = b_i - a_i + \beta (\mathbf{G}\mathbf{a})_i$$

$$\longrightarrow \quad \mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b} = \sum_{p=0}^{+\infty} \beta^p \mathbf{G}^p \mathbf{b}$$

**assumption:** spectral radius  $\rho(\beta \mathbf{G})$  is smaller than 1

- guarantees matrix inversion
- ensures uniqueness and stability of equilibrium action [Ballester06]

## properties

- equilibrium related to Katz-Bonacich centrality
- payoff interdependency spreads indirectly through network

# Network games with linear-quadratic payoffs

- Pure-strategy Nash equilibrium (PSNE)

$$u_i = b_i a_i - \frac{1}{2} a_i^2 + \beta a_i \sum_{j \in \mathcal{V}} G_{ij} a_j \quad \longrightarrow \quad \frac{\partial u_i}{\partial a_i} = b_i - a_i + \beta (\mathbf{G}\mathbf{a})_i$$

$$\longrightarrow \quad \mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b} \stackrel{\mathbf{G} = \boldsymbol{\chi} \boldsymbol{\Lambda} \boldsymbol{\chi}^T}{=} \boldsymbol{\chi} (\mathbf{I} - \beta \boldsymbol{\Lambda})^{-1} \boldsymbol{\chi}^T \mathbf{b}$$

**assumption:** spectral radius  $\rho(\beta \mathbf{G})$  is smaller than 1

- guarantees matrix inversion
- ensures uniqueness and stability of equilibrium action [Ballester06]

## properties

- equilibrium related to Katz-Bonacich centrality
- payoff interdependency spreads indirectly through network
- action is filtered version of marginal benefit on graph

# Outline

- Background
  - learning network structure from data
  - network games with linear-quadratic payoffs
- Learning games with linear-quadratic payoffs
  - independent marginal benefits
  - homophilous marginal benefits
- Experimental results
- Discussion



# Learning with independent marginal benefits

Nash equilibrium

$$\mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b} \quad \longrightarrow \quad (\mathbf{I} - \beta \mathbf{G}) \mathbf{a} = \mathbf{b}$$

# Learning with independent marginal benefits

Nash equilibrium

$$\mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b} \quad \longrightarrow \quad (\mathbf{I} - \beta \mathbf{G}) \mathbf{a} = \mathbf{b}$$

consider  $K$  games

$$\mathbf{B} = [\mathbf{b}^{(1)}, \mathbf{b}^{(2)}, \dots, \mathbf{b}^{(K)}] \in \mathbb{R}^{N \times K} \quad \text{marginal}$$

$$\mathbf{A} = [\mathbf{a}^{(1)}, \mathbf{a}^{(2)}, \dots, \mathbf{a}^{(K)}] \in \mathbb{R}^{N \times K} \quad \text{action}$$

# Learning with independent marginal benefits

Nash equilibrium

$$\mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b} \quad \longrightarrow \quad (\mathbf{I} - \beta \mathbf{G}) \mathbf{a} = \mathbf{b}$$

consider  $K$  games

$$\mathbf{B} = [\mathbf{b}^{(1)}, \mathbf{b}^{(2)}, \dots, \mathbf{b}^{(K)}] \in \mathbb{R}^{N \times K} \quad \text{marginal}$$

$$\mathbf{A} = [\mathbf{a}^{(1)}, \mathbf{a}^{(2)}, \dots, \mathbf{a}^{(K)}] \in \mathbb{R}^{N \times K} \quad \text{action}$$

joint learning

$$\underset{\mathbf{G}, \mathbf{B}}{\text{minimize}} \quad f(\mathbf{G}, \mathbf{B}) = \|(\mathbf{I} - \beta \mathbf{G})\mathbf{A} - \mathbf{B}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \|\mathbf{B}\|_F^2,$$

$$\text{subject to} \quad G_{ij} = G_{ji}, \quad G_{ij} \geq 0, \quad G_{ii} = 0 \quad \text{for } \forall i, j \in \mathcal{V}, \\ \|\mathbf{G}\|_1 = N,$$

# Learning with independent marginal benefits

Nash equilibrium

$$\mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b} \quad \longrightarrow \quad (\mathbf{I} - \beta \mathbf{G}) \mathbf{a} = \mathbf{b}$$

consider  $K$  games

$$\mathbf{B} = [\mathbf{b}^{(1)}, \mathbf{b}^{(2)}, \dots, \mathbf{b}^{(K)}] \in \mathbb{R}^{N \times K} \quad \text{marginal}$$

$$\mathbf{A} = [\mathbf{a}^{(1)}, \mathbf{a}^{(2)}, \dots, \mathbf{a}^{(K)}] \in \mathbb{R}^{N \times K} \quad \text{action}$$

joint learning

$$\underset{\mathbf{G}, \mathbf{B}}{\text{minimize}} \quad f(\mathbf{G}, \mathbf{B}) = \|\mathbf{I} - \beta \mathbf{G}\|_F^{-2} \|\mathbf{A} - \mathbf{B}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \|\mathbf{B}\|_F^2,$$

$$\text{subject to} \quad G_{ij} = G_{ji}, \quad G_{ij} \geq 0, \quad G_{ii} = 0 \quad \text{for } \forall i, j \in \mathcal{V}, \\ \|\mathbf{G}\|_1 = N,$$

# Learning with independent marginal benefits

Nash equilibrium

$$\mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b} \quad \longrightarrow \quad (\mathbf{I} - \beta \mathbf{G}) \mathbf{a} = \mathbf{b}$$

consider  $K$  games

$$\mathbf{B} = [\mathbf{b}^{(1)}, \mathbf{b}^{(2)}, \dots, \mathbf{b}^{(k)}] \in \mathbb{R}^{N \times K} \quad \text{marginal}$$

$$\mathbf{A} = [\mathbf{a}^{(1)}, \mathbf{a}^{(2)}, \dots, \mathbf{a}^{(K)}] \in \mathbb{R}^{N \times K} \quad \text{action}$$

joint learning

$$\text{minimize}_{\mathbf{G}, \mathbf{B}} f(\mathbf{G}, \mathbf{B}) = \|\mathbf{I} - \beta \mathbf{G}\|_F^{-2} \|\mathbf{A} - \mathbf{B}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \|\mathbf{B}\|_F^2,$$

$$\text{subject to } G_{ij} = G_{ji}, G_{ij} \geq 0, G_{ii} = 0 \text{ for } \forall i, j \in \mathcal{V}, \\ \|\mathbf{G}\|_1 = N,$$

# Learning with independent marginal benefits

Nash equilibrium

$$\mathbf{a} = (\mathbf{I} - \beta \mathbf{G})^{-1} \mathbf{b} \quad \longrightarrow \quad (\mathbf{I} - \beta \mathbf{G}) \mathbf{a} = \mathbf{b}$$

consider  $K$  games

$$\mathbf{B} = [\mathbf{b}^{(1)}, \mathbf{b}^{(2)}, \dots, \mathbf{b}^{(k)}] \in \mathbb{R}^{N \times K} \quad \text{marginal}$$

$$\mathbf{A} = [\mathbf{a}^{(1)}, \mathbf{a}^{(2)}, \dots, \mathbf{a}^{(K)}] \in \mathbb{R}^{N \times K} \quad \text{action}$$

joint learning

$$\text{minimize}_{\mathbf{G}, \mathbf{B}} f(\mathbf{G}, \mathbf{B}) = \|\mathbf{I} - \beta \mathbf{G}\|_F^{-2} \|\mathbf{A} - \mathbf{B}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \|\mathbf{B}\|_F^2,$$

$$\text{subject to } G_{ij} = G_{ji}, G_{ij} \geq 0, G_{ii} = 0 \text{ for } \forall i, j \in \mathcal{V}, \\ \|\mathbf{G}\|_1 = N,$$

# Learning with independent marginal benefits

joint learning

$$\begin{aligned} & \underset{\mathbf{G}, \mathbf{B}}{\text{minimize}} & f(\mathbf{G}, \mathbf{B}) &= \|\mathbf{I} - \beta \mathbf{G}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \|\mathbf{B}\|_F^2, \\ & \text{subject to} & & G_{ij} = G_{ji}, G_{ij} \geq 0, G_{ii} = 0 \text{ for } \forall i, j \in \mathcal{V}, \\ & & & \|\mathbf{G}\|_1 = N, \end{aligned}$$

# Learning with independent marginal benefits

## joint learning

$$\begin{aligned} \underset{\mathbf{G}, \mathbf{B}}{\text{minimize}} \quad & f(\mathbf{G}, \mathbf{B}) = \|\mathbf{I} - \beta \mathbf{G}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \|\mathbf{B}\|_F^2, \\ \text{subject to} \quad & G_{ij} = G_{ji}, G_{ij} \geq 0, G_{ii} = 0 \text{ for } \forall i, j \in \mathcal{V}, \\ & \|\mathbf{G}\|_1 = N, \end{aligned}$$

## remarks

- quadratic programming jointly convex in  $\mathbf{G}$  and  $\mathbf{B}$



# Learning with independent marginal benefits

## joint learning

$$\begin{aligned} & \underset{\mathbf{G}, \mathbf{B}}{\text{minimize}} \quad f(\mathbf{G}, \mathbf{B}) = \|\mathbf{I} - \beta \mathbf{G}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \|\mathbf{B}\|_F^2, \\ & \text{subject to} \quad G_{ij} = G_{ji}, G_{ij} \geq 0, G_{ii} = 0 \text{ for } \forall i, j \in \mathcal{V}, \\ & \quad \|\mathbf{G}\|_1 = N, \end{aligned}$$

## remarks

- quadratic programming jointly convex in  $\mathbf{G}$  and  $\mathbf{B}$
- spectral radius  $\rho(\beta \mathbf{G})$  impact learning performance
  - approaching 0: action independent from graph structure
  - approaching 1: action related to eigenvector centrality

# Learning with independent marginal benefits

## joint learning

$$\begin{aligned} \underset{\mathbf{G}, \mathbf{B}}{\text{minimize}} \quad & f(\mathbf{G}, \mathbf{B}) = \|\mathbf{I} - \beta \mathbf{G}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \|\mathbf{B}\|_F^2, \\ \text{subject to} \quad & G_{ij} = G_{ji}, G_{ij} \geq 0, G_{ii} = 0 \text{ for } \forall i, j \in \mathcal{V}, \\ & \|\mathbf{G}\|_1 = N, \end{aligned}$$

## remarks

- quadratic programming jointly convex in  $\mathbf{G}$  and  $\mathbf{B}$
- spectral radius  $\rho(\beta \mathbf{G})$  impact learning performance
  - approaching 0: action independent from graph structure
  - approaching 1: action related to eigenvector centrality
- other factors: number of games, noise level, network density

# Learning with independent marginal benefits

---

**Algorithm 1** Learning Games with Independent Marginal Benefits

---

**Input:** Actions  $\mathbf{A} \in \mathbb{R}^{N \times K}$  for  $K$  games,  $\beta, \theta_1, \theta_2$

**Output:** Network  $\mathbf{G} \in \mathbb{R}^{N \times N}$ , marginal benefits  $\mathbf{B} \in \mathbb{R}^{N \times K}$  for  $K$  games

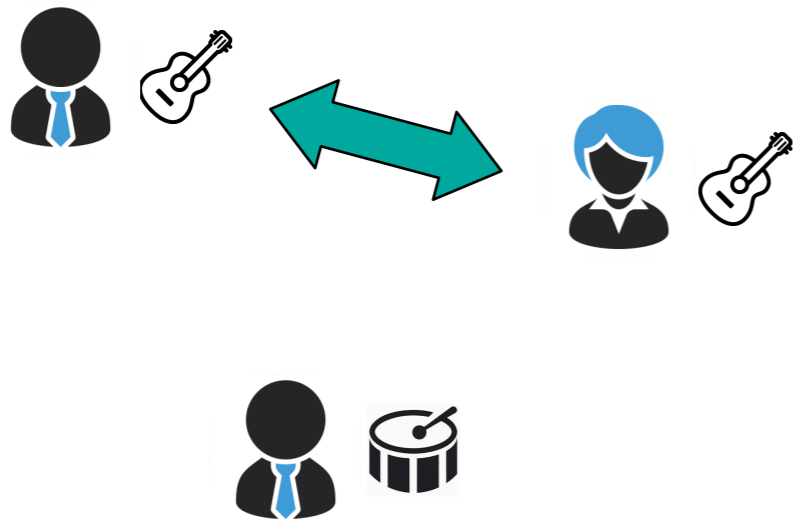
Solve for  $\mathbf{G}$  and  $\mathbf{B}$  in Eq. (5)

**return:**  $\mathbf{G}, \mathbf{B}$

---

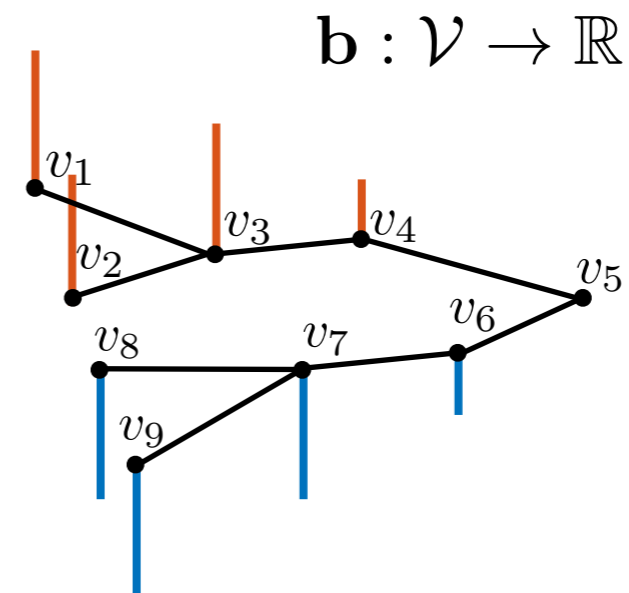
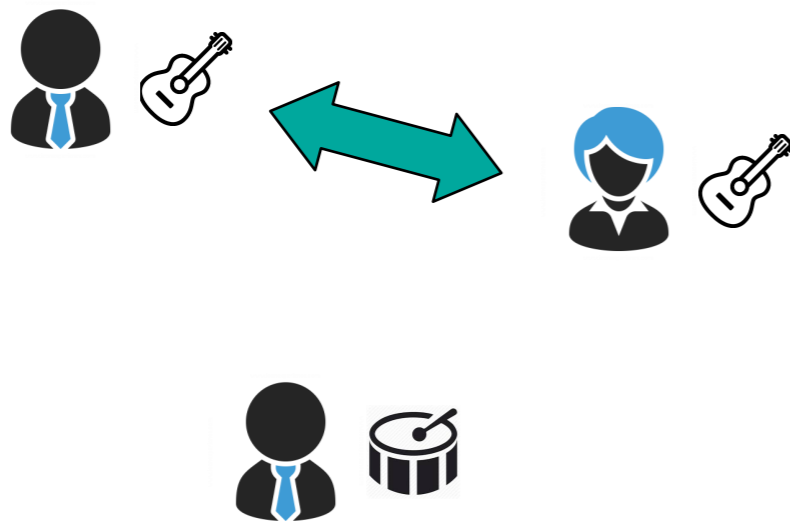
# Learning with homophilous marginal benefits

- Phenomenon of homophily in social networks [McPherson01]



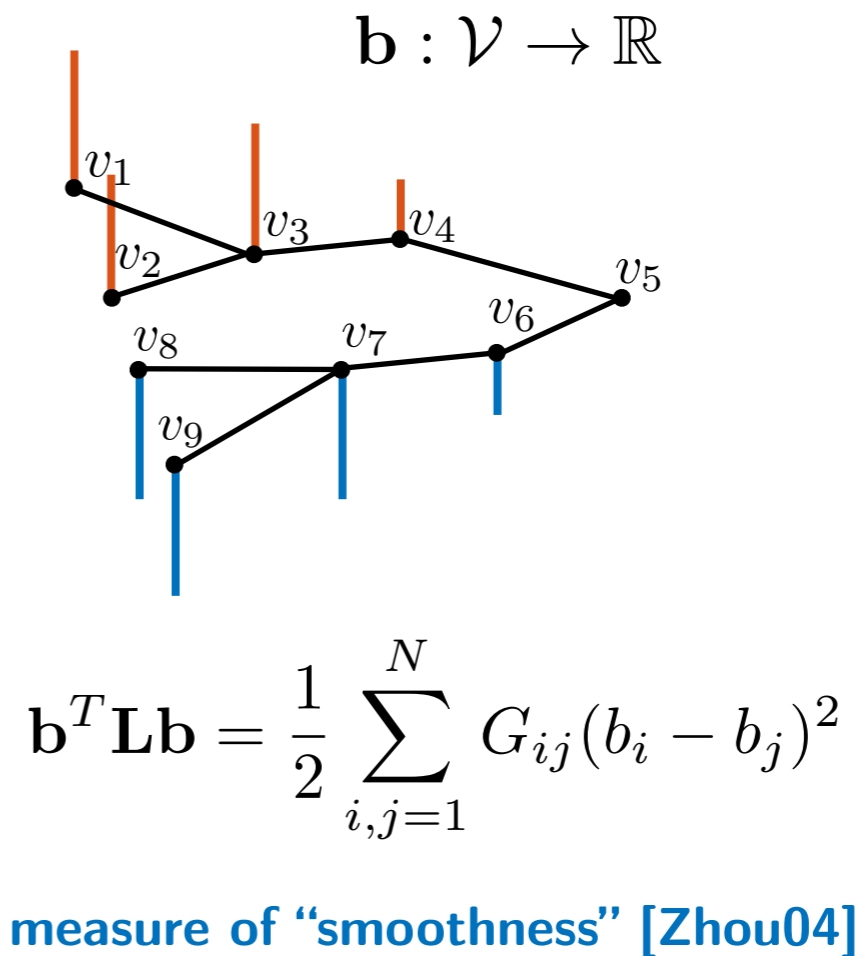
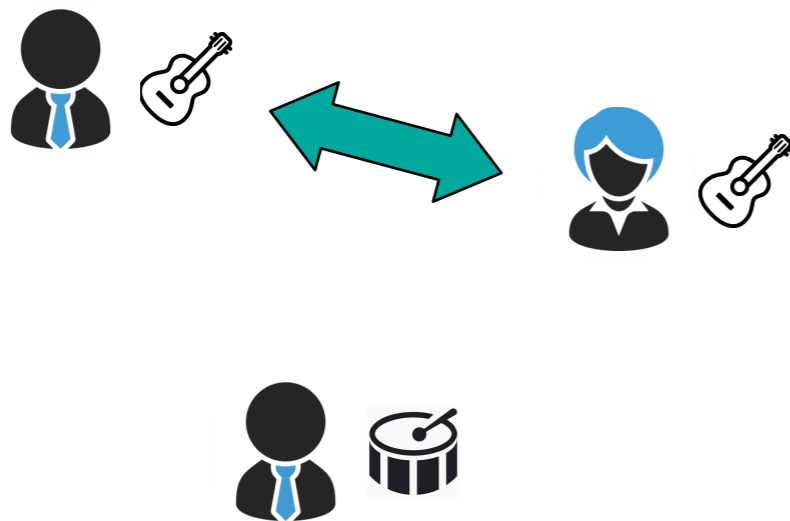
# Learning with homophilous marginal benefits

- Phenomenon of homophily in social networks [McPherson01]
- Given homophily marginal benefits are **smooth** functions on graph



# Learning with homophilous marginal benefits

- Phenomenon of homophily in social networks [McPherson01]
- Given homophily marginal benefits are **smooth** functions on graph



# Learning with homophilous marginal benefits

joint learning

$$\begin{aligned} & \underset{\mathbf{G}, \mathbf{B}}{\text{minimize}} \quad h(\mathbf{G}, \mathbf{B}) = \|\mathbf{I} - \beta \mathbf{G}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \text{tr}(\mathbf{B}^T \mathbf{L} \mathbf{B}), \\ & \text{subject to} \quad G_{ij} = G_{ji}, G_{ij} \geq 0, G_{ii} = 0 \text{ for } \forall i, j \in \mathcal{V}, \\ & \quad \|\mathbf{G}\|_1 = N, \\ & \quad \mathbf{L} = \text{diag}\left(\sum_{j \in \mathcal{V}} G_{ij}\right) - \mathbf{G} \end{aligned}$$

# Learning with homophilous marginal benefits

## joint learning

$$\begin{aligned} & \underset{\mathbf{G}, \mathbf{B}}{\text{minimize}} & h(\mathbf{G}, \mathbf{B}) &= \|\mathbf{I} - \beta \mathbf{G}\|_F^2 + \theta_1 \|\mathbf{G}\|_F^2 + \theta_2 \text{tr}(\mathbf{B}^T \mathbf{L} \mathbf{B}), \\ & \text{subject to} & & G_{ij} = G_{ji}, G_{ij} \geq 0, G_{ii} = 0 \text{ for } \forall i, j \in \mathcal{V}, \\ & & & \|\mathbf{G}\|_1 = N, \\ & & & \mathbf{L} = \text{diag}\left(\sum_{j \in \mathcal{V}} G_{ij}\right) - \mathbf{G} \end{aligned}$$

## remarks

- not jointly convex in  $\mathbf{G}$  and  $\mathbf{B}$
- convex in subproblems of solving for one while fixing other



# Learning with homophilous marginal benefits

---

**Algorithm 2** Learning Games with Homophilous Marginal Benefits

---

**Input:** Actions  $\mathbf{A} \in \mathbb{R}^{N \times K}$  for  $K$  games,  $\beta, \theta_1, \theta_2$

**Output:** Network  $\mathbf{G} \in \mathbb{R}^{N \times N}$ , marginal benefits  $\mathbf{B} \in \mathbb{R}^{N \times K}$  for  $K$  games

**Initialize:**  $\mathbf{B}_0(:, k) \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$  for  $k = 1, \dots, K, t = 1, \Delta = 1$

**if**  $\Delta \geq 10^{-4}$  and  $t \leq \#$  iterations **then**

Solve for  $\mathbf{G}_t$  in Eq. (7) given  $\mathbf{B}_{t-1}$

Compute  $\mathbf{L}_t$  using  $\mathbf{G}_t$

$\mathbf{B}_t = (\mathbf{I} + \theta_2 \mathbf{L}_t)^{-1} (\mathbf{I} - \beta \mathbf{G}_t) \mathbf{A}$

$\Delta = |h(\mathbf{G}_t, \mathbf{B}_t) - h(\mathbf{G}_{t-1}, \mathbf{B}_{t-1})|$  (for  $t > 1$ )

$t = t + 1$

**end if**

**return:**  $\mathbf{G} = \mathbf{G}_t, \mathbf{B} = \mathbf{B}_t$ .

---

# Outline

- Background
  - learning network structure from data
  - network games with linear-quadratic payoffs
- Learning games with linear-quadratic payoffs
  - independent marginal benefits
  - homophilous marginal benefits
- Experimental results
- Discussion

# Experiments on synthetic data

- Random graphs with 20 nodes
  - Erdős-Rényi (ER): edges created independently with certain probability
  - Watts-Strogatz (WS): regular graph followed by random rewiring
  - Barabási-Albert (BA): graph generated using preferential attachment

# Experiments on synthetic data

- Random graphs with 20 nodes
  - Erdős-Rényi (ER): edges created independently with certain probability
  - Watts-Strogatz (WS): regular graph followed by random rewiring
  - Barabási-Albert (BA): graph generated using preferential attachment
- Compute  $\beta$  so that  $\rho(\beta\mathbf{G}) \in (0, 1)$
- Initialise marginal benefits for 50 games
  - homophilous:  $\mathbf{b} \sim \mathcal{N}(\mathbf{0}, \mathbf{L}^\dagger + \frac{1}{10}\mathbf{I})$
- Generate equilibrium actions:  $\mathbf{a} = (\mathbf{I} - \beta\mathbf{G})^{-1} \mathbf{b}$

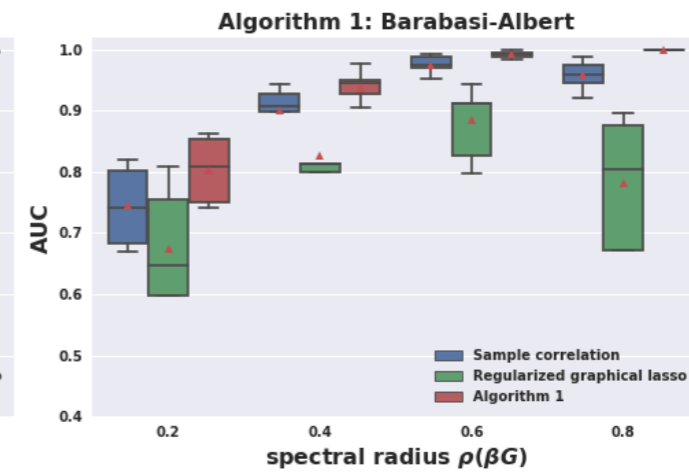
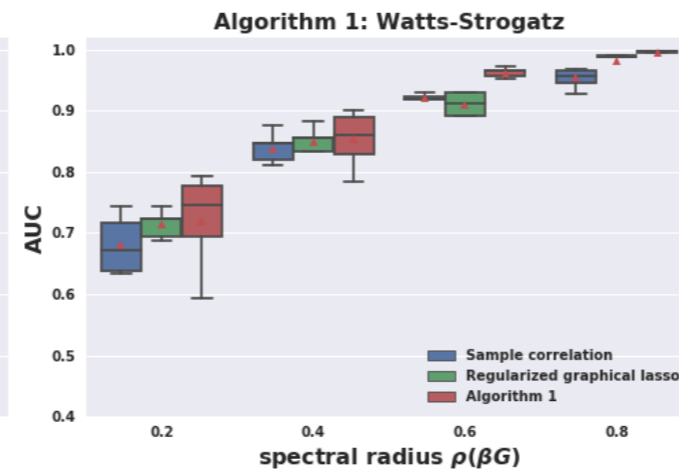
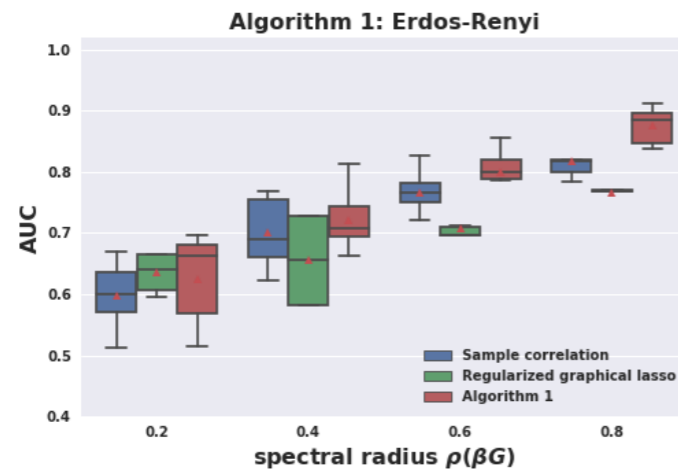
# Setting

- Evaluate on area under the curve (AUC)
- Baselines
  - sample correlation as edge weights
  - graph learned by regularised graphical Lasso [Lake10]

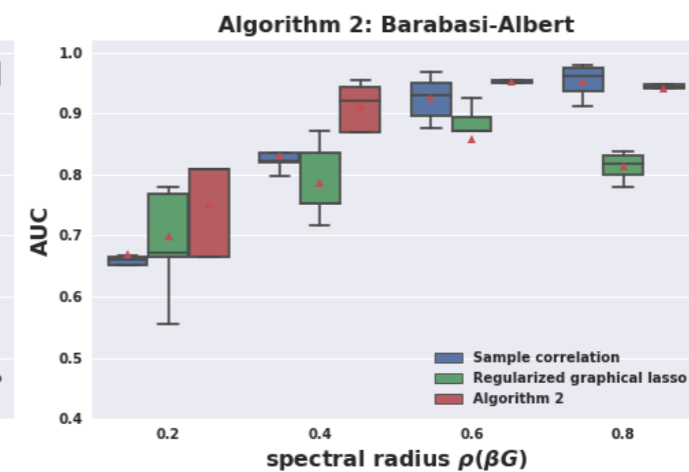
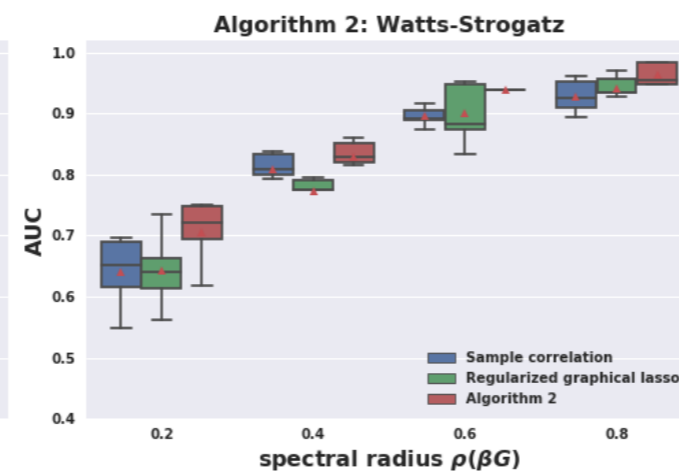
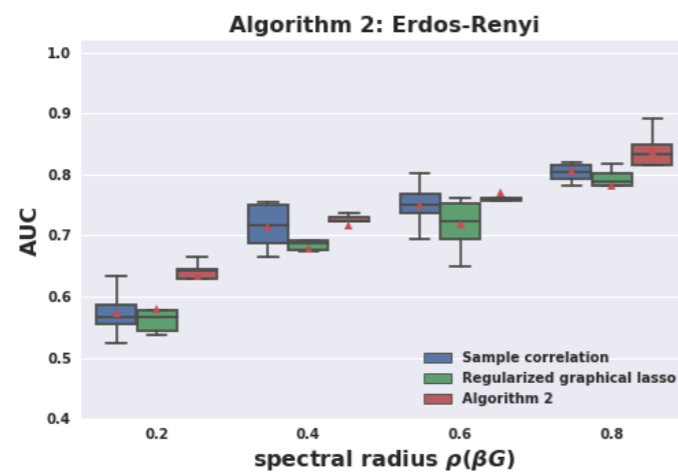
$$\begin{aligned} & \underset{\Theta, \sigma^2}{\text{maximize}} && \log \det \Theta - \text{tr} \left( \frac{1}{M} \mathbf{X} \mathbf{X}^T \Theta \right) - \rho \|\Theta\|_1, \\ & \text{subject to} && \Theta = \mathbf{L} + \frac{1}{\sigma^2} \mathbf{I}, \quad \mathbf{L} \in \mathcal{L}, \end{aligned}$$

# Learning interaction network

## independent marginal benefits

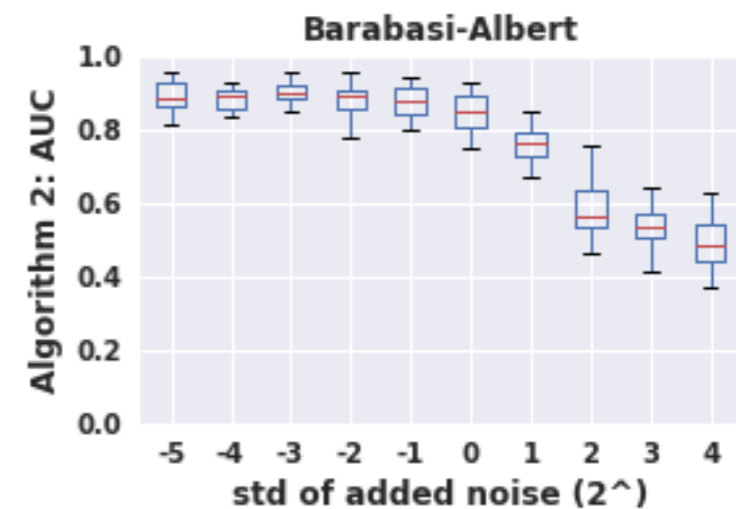
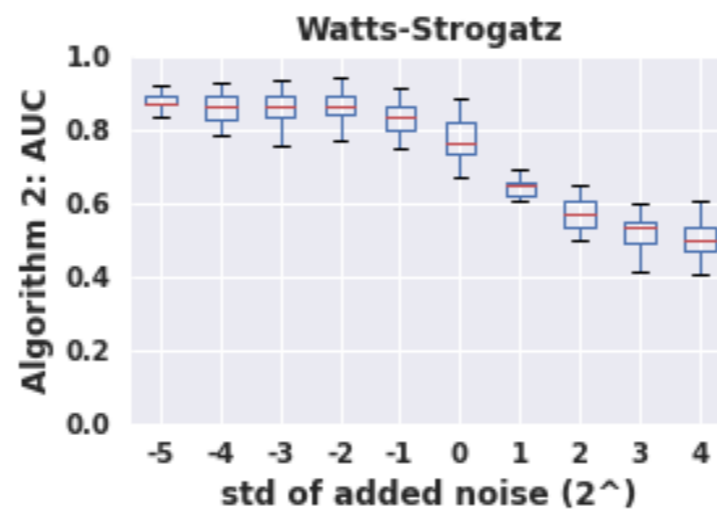
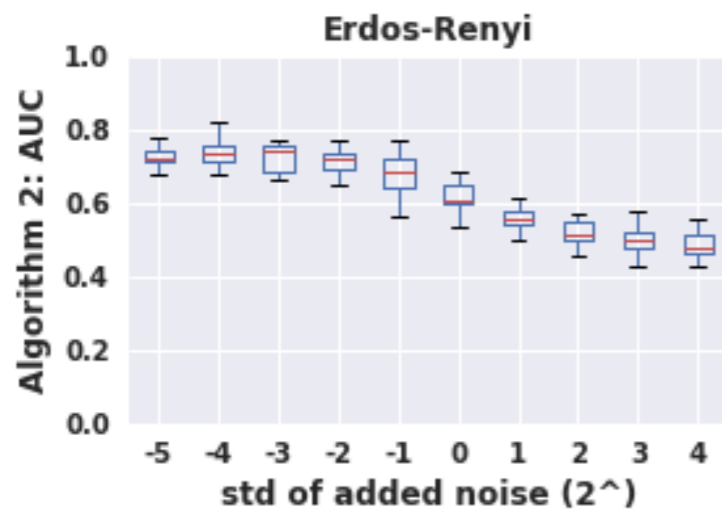
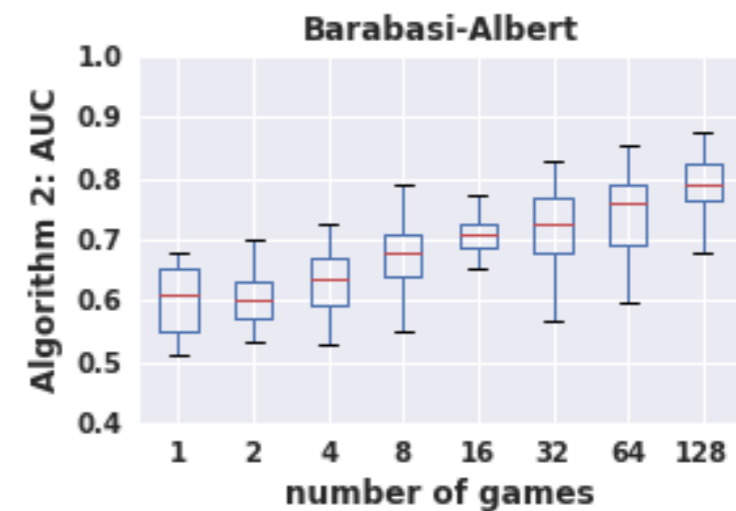
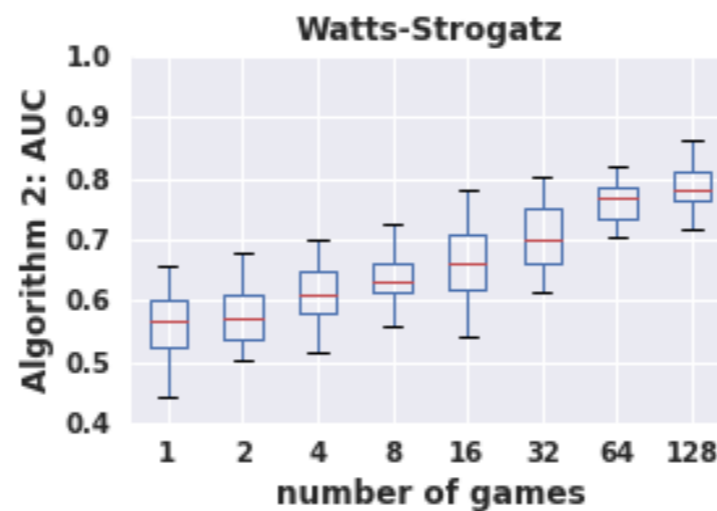
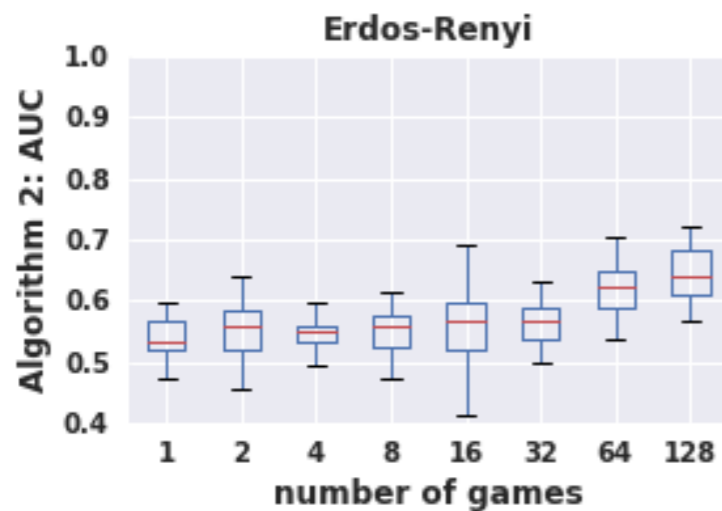


## homophilous marginal benefits



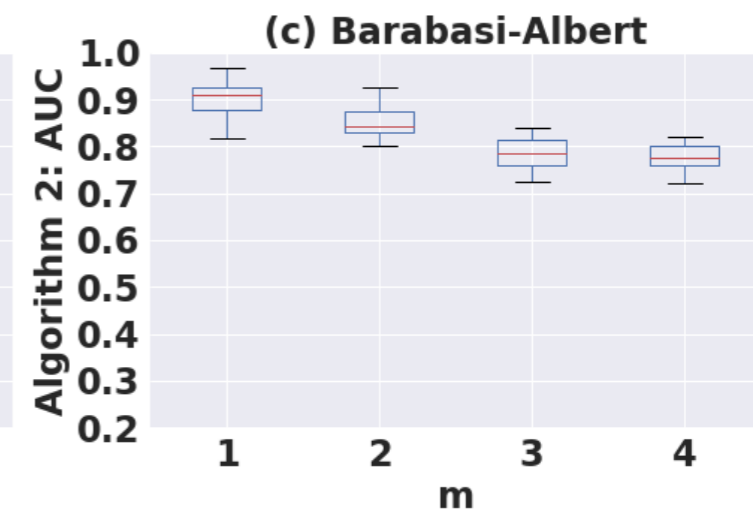
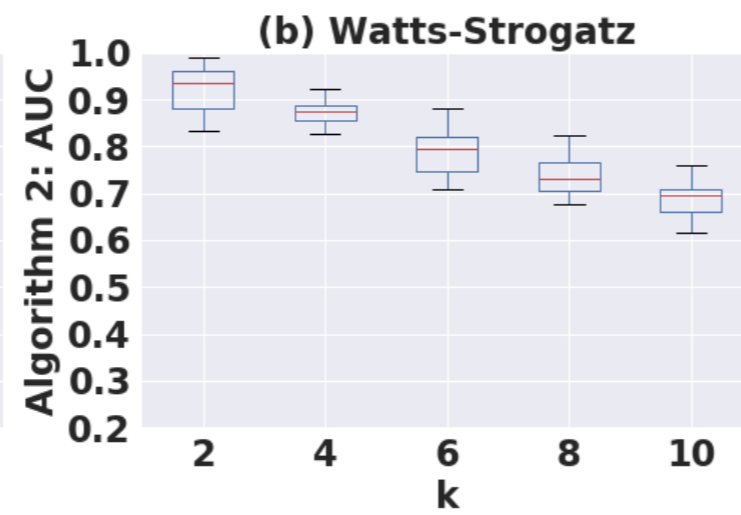
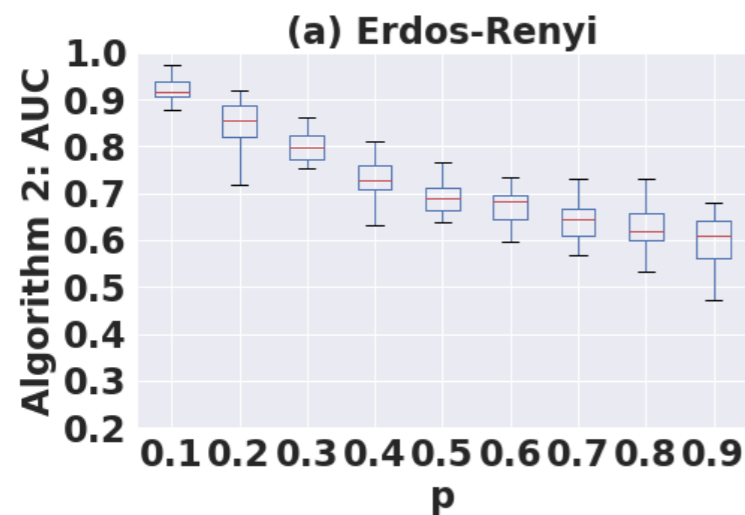
# Performance vs. # games & noise

- Homophilous marginal benefits with  $\rho(\beta\mathbf{G}) = 0.6$



# Performance vs. network structure

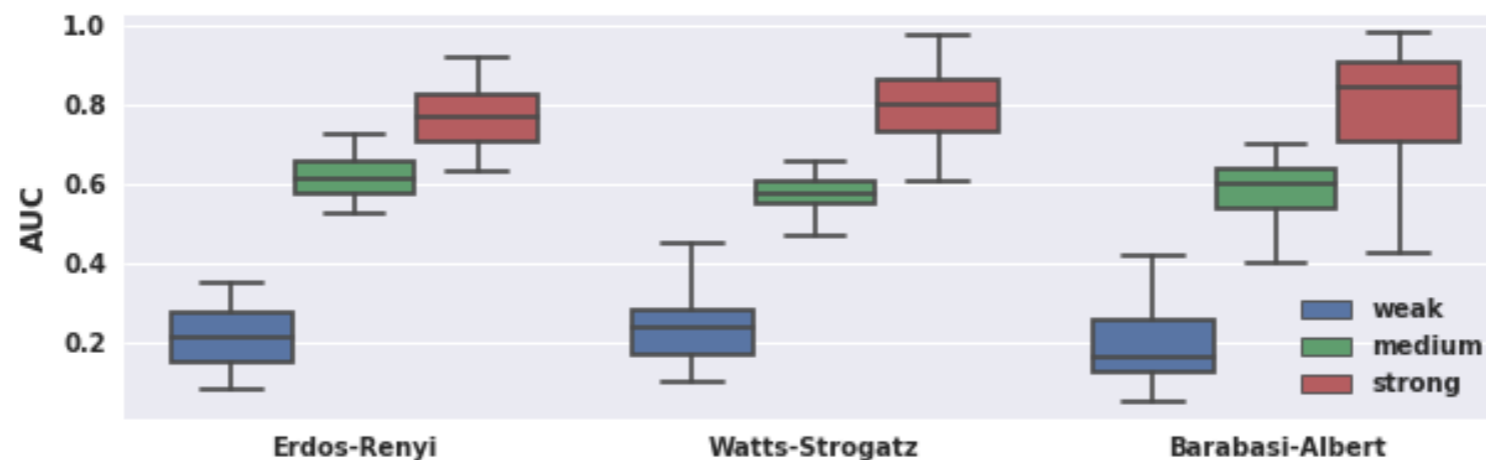
- Homophilous marginal benefits with  $\rho(\beta\mathbf{G}) = 0.6$
- Parameters in random graph models
  - ER: each node pair connected with probability  $p$
  - WS:  $k$ -regular graph with rewiring probability  $p$
  - BA:  $m$  nodes added at each graph generation step





# Performance vs. strength of homophily

- Homophilous marginal benefits with  $\rho(\beta\mathbf{G}) = 0.6$
- Marginal benefits  $B$  as linear combinations of 1st-5th (strong homophily), 6th-10th (medium), 11th-15th (weak) eigenvectors of graph Laplacian



# Learning marginal benefits

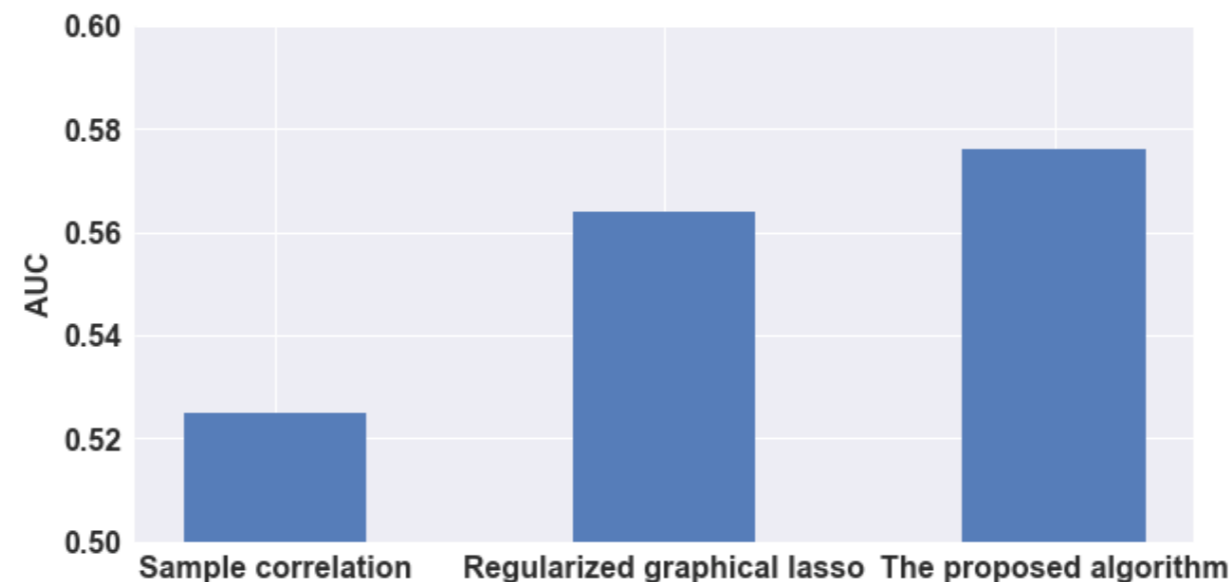
- Compare groundtruth and learned marginal benefits using coefficients of determination ( $R^2$ )

Table 1: Performance (in terms of  $R^2$ ) of learning marginal benefits.

	Algorithm 1		Algorithm 2	
	mean	std	mean	std
ER graph	0.959	0.005	0.982	0.002
WS graph	0.955	0.007	0.921	0.010
BA graph	0.937	0.008	0.909	0.010

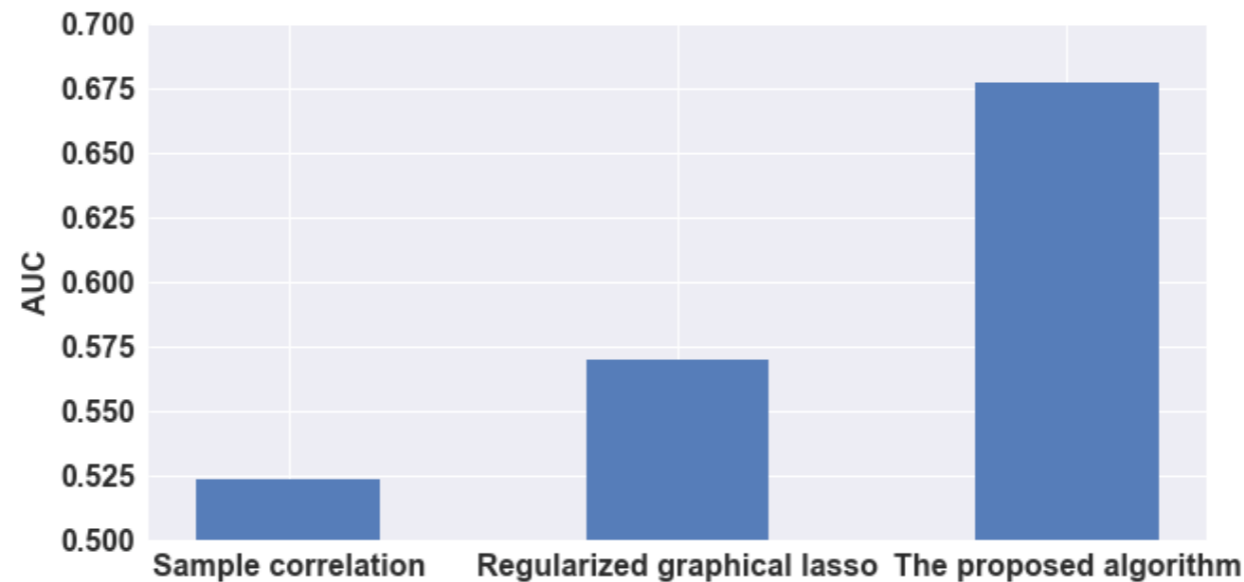
# Experiments on real world data

- Learning social network
  - players: 182 households in a village in rural India [Banerjee13]
  - actions in 31 games: number of facilities adopted by each household
  - strategic complements: conformity to social norms (decisions made by neighbours)
  - compare with groundtruth: self-reported friendship



# Experiments on real world data

- Learning trade network
  - players: 235 countries
  - actions in 192 games: import/export of 96 products of countries in 2008
  - strategic substitutes: complementary demand/supply leads to nonsmooth signals on trade network
  - compare with groundtruth: trade network of countries in 2002



# Outline

- Background
  - learning network structure from data
  - network games with linear-quadratic payoffs
- Learning games with linear-quadratic payoffs
  - independent marginal benefits
  - homophilous marginal benefits
- Experimental results
- Discussion

# Discussion

- Applications in practical scenarios
  - detect communities of players (for stratification)
  - compute centrality measures (for efficient targeting strategies)
  - design intervention mechanisms to achieve planning objective
    - ◆ maximise total utilities of players (via adjusting marginal benefits) [Galeotti17]
    - ◆ reduce inequality between players (via adjusting interaction network)

# Discussion

- Applications in practical scenarios
  - detect communities of players (for stratification)
  - compute centrality measures (for efficient targeting strategies)
  - design intervention mechanisms to achieve planning objective
    - ◆ maximise total utilities of players (via adjusting marginal benefits) [Galeotti17]
    - ◆ reduce inequality between players (via adjusting interaction network)
- Open issues & future directions
  - determination of  $\beta$  (strength of strategic interaction)
  - probabilistic interpretation of learning framework
  - theoretical understanding, e.g., recovery guarantee
  - more general payoff functions
  - real-world intervention