36-350: Data Mining

Handout 4 September 8, 2003

Finding the important dimensions in data

Similarity searching tells you the local structure of a dataset. But we also want to know the global structure. For example: What are the words which distinguish the auto/moto groups? What are the colors which distinguish the sailing/racing groups?

An **important** dimension is very **informative** about what group an object belongs to. Intuitively, this means that each group tends to have a distinct value on that dimension. For example, a word is important if it is more common in one group of documents than another.

Let x be a dimension and x be a particular value. The value x is informative if it is more likely to occur in one group than another. Let c be the group, so that c = 1 is the first group and c = 2 the second group. Then x is informative if

$$p(x = x \mid c = 1) \neq p(x = x \mid c = 2)$$

The entire dimension x is informative if its values tend to be informative.

This intuition can be represented formally by Bayes' rule:

$$p(c = c \mid x) = \frac{p(x = x \mid c = c)p(c = c)}{p(x = x)}$$

$$\frac{p(c = 1 \mid x = x)}{p(c = 2 \mid x = x)} = \frac{p(x = x \mid c = 1)}{p(x = x \mid c = 2)} \frac{p(c = 1)}{p(c = 2)}$$

p(c) is our uncertainty about c before observing x, and p(c|x) is our uncertainty after observing x. Thus the ratio $p(x = \mathbf{x} \mid c = 1)/p(x = \mathbf{x} \mid c = 2)$ describes what we learn about c from observing $x = \mathbf{x}$.

Measuring information

Entropy is a measure of uncertainty (in bits):

$$\begin{split} \mathcal{H}(c) &=& -\sum_{\mathbf{C}} p(c = \mathbf{c}) \log_2 p(c = \mathbf{c}) \\ \mathcal{H}(c \mid x) &=& -\sum_{\mathbf{C}} p(c = \mathbf{c} \mid x) \log_2 p(c = \mathbf{c} \mid x) \end{split}$$

Entropy is large when p(c) is flat (totally uncertain) and is zero when p(c) is concentrated on one value (totally certain). Examples:

$$\begin{array}{c|cccc} p(c=1) & p(c=2) & H(c) \\ \hline 1/2 & 1/2 & 1 \text{ bit} \\ 1/3 & 2/3 & 0.918 \text{ bits} \\ 0 & 1 & 0 \text{ bits} \\ \end{array}$$

Information is the change in uncertainty:

$$\mathcal{I}(c, x = \mathbf{x}) = \mathcal{H}(c) - \mathcal{H}(c|x = \mathbf{x})$$
 (actual information)

This is the information in a particular value x. The information in the entire dimension is the average information in each value:

$$\mathcal{I}(c,x) = \sum_{\mathbf{x}} p(x = \mathbf{x}) \mathcal{I}(c,x = \mathbf{x})$$
 (expected information)
$$= \mathcal{H}(c) - \sum_{\mathbf{x}} p(x = \mathbf{x}) \mathcal{H}(c|x = \mathbf{x})$$

Entropy is called **self information** because $\mathcal{I}(c,c) = \mathcal{H}(c)$.

Uncertainty usually decreases, but can also increase. For example, on a random day, it is unlikely to rain, so the uncertainty of "rain" is low, say 0.1 bits. But if you read a weather report giving a 50% chance of rain, your uncertainty increases to 1 bit. In these cases, the actual information is negative.

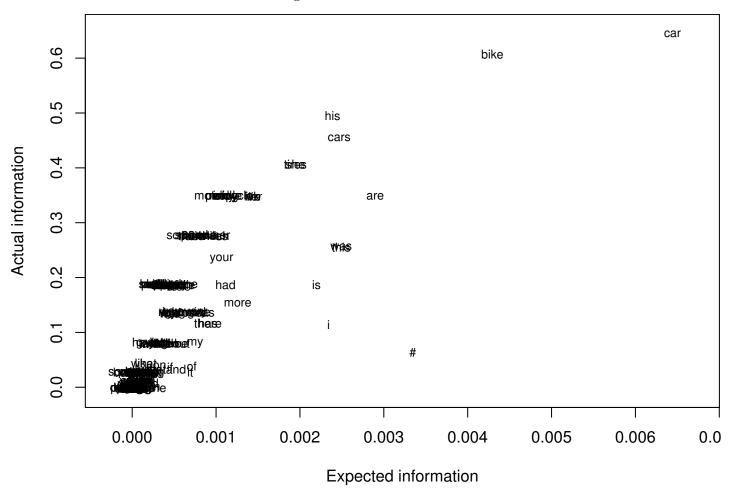
For example, suppose we pick a random position in a random document. Let x be 1 if the word is "car", and 0 otherwise. The frequencies for the 10 auto/moto documents are

For this table,

$$\mathcal{H}(c) = 0.997$$
 $\mathcal{H}(c|x = \text{``car''}) = 0$
 $\mathcal{H}(c|x = \text{not ``car''}) = 0.996$
 $p(x = \text{``car''}) = 0.01$
 $\mathcal{I}(c,x) = 0.997 - (0.01*0) - (0.99*0.996) = 0.01$

How to find the important words:

- 1. Collect counts for each class (only need prototypes)
- 2. For each word, collect a subtable of counts (no IDF or other weighting)
- 3. Compute the expected information in each subtable. Alternatively, compute the actual information for the word having occurred.



Results:

- Actual information is better at picking the words we intuitively think of as distinguishing the groups.
- Expected information tends to favor frequent words.
- Expected information is similar to performing a χ^2 independence test on each subtable.