# Compilation of Data on the Current TEC Analog <br> Electronics 

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## I) Overview

In order to avoid chaos and unnecessary entropy increase, all important information on the TEC analog circuitry has been assembled in this writeup. The "conventional" TEC analog system is diagrammed in Fig. (l) on the following page. Section II) of this report sketches the preamplifier models in current use, and Section III) describes additional circuitry needed to shape and process the signals. Each circuit descrintion contains a brief writeup, schematic, and, if oertinent, print layouts and additional diagrams. Component placement is not indicated on the print layouts; one must use an existing prototype or production model for reference.

Figure 1

## ELECTRONICS (ANALOG)

## PRECISION WIRE



## II) TEC Preamplifiers

All designs in use are based upon a common-emitter-w. feedback first stage (CE-3) amplifier cascaded with a common-base second stage (CB-4). The first-stage is kept inside the gas volume of the test chamber and it drives a $100 \Omega$ twisted pair approx. 40 cm . to the exterior of the chamber, series terminated into the second-stage input. The second-stage outputs drive $50 \Omega$ cables to the counting room for further manioulation. Design details follow....

II-A) CE-3 Conventional first-stage preamplifier
The schematic (Fig. 2) shows the anode (ootimized for negative input signals), and PW (optimized for positive inout signals) circuits; identical except for the use of NPN transistors in the former, and PNP in the latter. The output currently drives a $100 \Omega$ twisted pair to a $C B-4$ second stage; if a CB-4 is not used, one must $D C$ isolate the termination resistor from the line via a series capacitor. All transistors are SOT-23 $\mu$-chips. This is an inverting, current-sensitive amplifier.

The printed circuit (Fig. 3) contains one anode and two PW circuits.

Specs.
Rise-time: $\tau_{r} \simeq 3 . n \sec$.
Noise: $\simeq 2000 \mathrm{e}^{-}$RMS over full bandwith
Input Impedance: $Z_{i n} \simeq 140 \Omega$ (inc. input resistor)
Power Diss.: $P_{D}=13 \mathrm{~mW} /$ channel
Gain: Anode: $32 \mathrm{~dB}=5 \mathrm{mV} / \mu \mathrm{A}$ (Assuming above input impedance)
$\mathrm{PW}: 29 \mathrm{~dB}=4 \mathrm{mV} / \mu \mathrm{A}$

## FIRST STAGE PREAMPLIFIER

## CE 3



$$
\frac{Z_{\text {in }} \sim 140 \Omega}{P_{0}}=12 \mathrm{~mW} / \text { channel }
$$

Figure 3



Back side
(9)


Comnonent side

POSITIVE

II-B) CB-4 Conventional Second-stage amplifier
The schematic (Fig. 4) shows the anode (optimized for positive input signals) and PW (ontimized for negative input signals) designs. The $C B-4$ is intended to be driven by the $C E-3$ outputs, and it will drive $50 \Omega$ cables.

Note: Each amplifier will drive up to $\geq 2$ volts in the optimized direction into $50 \Omega$, however the linearity of the cascade degrades after 500 mV of output (ref. writeup by $H$. Anders et. al.). The TEC is generally run below this limit, but if larger range is desired, a common-emitter-feedback stage (analagous to the first stage) may be a better choice. One could as well consider using a fast monolithic for the second stage; however until techonology improves further, it is best to keep the head amplifier (which is performance-critical) discrete.

The printed circuit layout (Fig. 5) contains one anode and two PW circuits.

Specs....
Rise-time: $\tau_{x} \leqslant 3 \mathrm{nsec}$.
Input impedance: $Z_{i n} \simeq 100 \Omega$ (primarily the termination resistor)
Power Diss.: $P_{D}=140 \mathrm{~mW} /$ channel
Gain: Anode: 13 dB
PW: 12 dB
Gain of $C E-3 / C B-4$ cascade ( 2 mV in $\mathrm{CE}-3,320 \mathrm{mV}$ out $\mathrm{CB}-4$ ):
Anode: $44 \mathrm{~dB}=22 \mathrm{mV} / \mu \mathrm{A}$
$\mathrm{PW}: 40 \mathrm{~dB}=15 \mathrm{mV} / \mu \mathrm{A}$

## SECOND STAGE PREAMPLIFIER

CB 4


Figure 5


II-C) CE-3A All-anode first-stage preamplifier
As seen in the schematic (Fig. 6), this circuit is identical to the CE-3 design, except for the the print layout (Fig. 7), which contains 3 anode channels (the two PW channels of the $C E-3$ are replaced). This circuit is intended to drive a CB-4A.

## Figure 6

## FIRST STAGE PREAMPLIFIER

## CE 3A


$\frac{Z_{\text {in }} \sim 140 \Omega}{P_{0}=12 \mathrm{~mW} / \text { channel }}$


Back side


Component side

POSITIVE

II-D) CB-4A All-anode second-stage amplifier

As seen in the schematic (Fig. 8), this circuit is identical to the CB-4 design, except for the print layout (Fig. 9), which contains 3 anode channels ( the two PW channels of the CB-4 have been replaced). This circuit is intended to be driven by a CE-3A.

## Figure 8

## SECOND STAGE PREAMPLIFIER



NPN = BFR 90/91
$P N P=B F Q 23$

Figure 9


Comoonent side


Back side

## II-E) , CE-3P First-stage preamplifier with improved PW protection

In order to better protect the PW channels (which seem prone to destructive breakdown), a modification of the CE-3 pickup channels was made, where an anode-type NPN front-end replaced the PW PNP front-ends (which seemed more breakdownsensitive). This required an additional PNP transistor per PW channel to buffer the NPN output and drive the negative PW output signals down the $100 \Omega$ twisted pair. This transistor, however, raises the quiescent power dissipation of the PW channels to approx. $24 \mathrm{~mW} / \mathrm{ch} a n n e l$. The anode circuit remains unaltered. The schematic is given in Fig.l0), but no print layout exists, since the modification was handwired onto the CE-3 boards. Due to better performance of the NPN front-end, this circuit yields about 3 dB more gain in the PW channels over the conventional CE-3.

## FIRST STAGE PREAMPLIFIER


III) OTHER IMPORTANT CIRCUITS

III-A) Differential Amplifier
Fig. Il is a schematic of the circuit used to subtract the two PW signals. The inverting and non-inverting inputs to Al are balanced via two trimmer potentiometers (accessable at the front panel). Trimmer capacitor $T 1$ is adjusted to null any overshoot at the amplifier output. The amplifier rise-time is under 10 nsecs., and the "l-2" output will drive up to $\pm 1$ volt $\mathrm{P}-\mathrm{P}$ into a $50 \Omega$ load.

Figs. 12 and 13 are the PC layout for a quad NIM module.


Figure 12




Conwonent side

Fig. 14 is a block diagram of the circuit used to shape both anode and PWD (Pickup-Wire Difference) signals. The first stage is a pole/zero differentiation (5-10 nsec) which clips the input signal and attenuates any RC tail from the amplifier response. This is followed by a fixed gain stage to restore the signal amplitude, whereupon another pole/zero ( $\tau \simeq 500$ nsec.) is applied to compensate for the slow ion tail. The signal can then be integrated if desired, and the gain and baseline of the output stage can be adjusted to fit any FADC input requirements. A baseline restorer is in DC feedback around the output stage to compensate for any DC shifts. The schematic is given in Fig. 15.

Fig. 16 shows the location of all shaper adjustments on the printed circuit. The differentiation time-constant (TC) of the first stage is adjusted to the point at which the signal begins to be attenuated; the corresponding pole/zero ( $P Z$ ) constant is adjusted to remove any undershoot (at the $10-20 \mathrm{nsec}$. level). The second-stage $T C$ and $P Z$ are then adjusted to remove the slow ( $\simeq 500$ nsec.) tail; the $T C$ controls the timing at whtch the correction has effect (and must be adjusted to "balance" the timing of the signal tail), and the $P Z$ compensates for over/undershoot. There is a slight correlation between firstand second-stage differentiations; the process sketched above should be repeated for optimum shaping.

The integration stage is not currently used (both pots full off \{where there is no effect\}), but if desired, these pots may be trimmed to "smooth" the signal.

All of the above adjustments should be performed with the gain pot set near minimum. After the signal shape is adjusted, use this pot to bring the signal amplitude up to the desired level.

The DC bias level at the output is adjusted $0 \rightarrow \pm 1$ Volt by the bias pot. The baseline restorer compensation pot should be adjusted to the point at which the shaper output begins to oscillate, and then backed off to a "pinch" after the oscillation ceases. It's always good practice to make this adjustment first (especially if the shaper is oscillating; this is generally why). The hardware strap indicated in Fig. 15 selects a positive or negative bias increment (at present all units are wired positive).

The shaper accepts either polarity input signals up to $\simeq 300 \mathrm{mV} P-P$ (beware of input stage saturation) and the output will drive over $\pm 1$ volt into a $50 \Omega$ load.

The output signal will rise in $\simeq 7 \mathrm{nsec}$.
Figs. 17 and 18 show the PC layout for a quad NIM module.

Figure 14

## GENERAL PURPOSE TEC SHAPER




Figure 16


Figure 17



III-(C) Fast Positive Fan-Out
Fig. 19 shows the schematic for a circuit which is designed to fan out the second-stage anode amolifier (positive) signals. One such input drives two independent non-inverting outputs and two independent inverting outputs. The outputs will drive over $l$ volt into a $50 \Omega$ load, and rise in under 3 nsec (non-inverting), and 5 nsec (inverting). The circuit drops $\simeq 30 \%$ in amplitude between input and outputs.

Figs. 20 and 21 show the PC layouts for a quad NIM module. One very useful feature of this circuit is that the same layout can be used to accept either positive or negative input signals. To accept negative inputs, one need only substitute PNP transistors for NPN's (and vice-versa) and reverse the supply voltages.

## Figure 19



Figure 20


Component side


Back side

This section presents 3 amplifier designs developed at BNL which prove puite useful in TEC applications.

IV-A) Common-Base Preamplifier
Fig. 22 shows the schematic and Fig. 23 the layout of a fast 2 -stage common-base current-sensitive preamplifier. The CE-3/CB-4 cascade superceeds this for our TEC work (the Pole/Zero correction required between the two common-base stages is a nuisance, especially when they are separated oy bu cm. of twisted pair). The circuit is nonetheless a classic, and is in use by the Hofer group at SIN.

Figure 22


Figure 23


Component side

IV-B) Slow Charge-Sensitive Preamplifier
Fig. 24 shows the schematic and Fig. 25 the PC layout of a slow (rise-time $\simeq 40$ nsecs) charge-sensitive amplifier (gain $=6600 \mathrm{e} / \mathrm{mV}$ ). This amplifier is used in our tests to monitor gas gain, thus is quite important. One must beware however; the layouts already prepared at ETH are actually backwards, hence the FET connections are convoluted.

## Figure 24



ALL TRANSISTORS IN SOCKETS
$T_{1}$ - SFB8558, BFEIT. 2N4861(TEXAS INSTR)
$r_{2.3}-2 N 3906$
$\mathrm{r}_{4} .5-2 \mathrm{~N}_{3} 9 \mathrm{~T}_{4}$
$r_{6}-2 N 4416$. OR FAST DIODE WITH I, $<10^{\circ-}$ A
OASHED......
INPUT CONNECTIONS ON TEFLON
STANDOFFS ANO SOCKETS.

(O)

## PIN 4 : KEY SLOT

$\mathrm{C}_{0}=0$ FOR wioeband measurements on
LOW CAPACITANCE ION CHAMBERS

Figure 25


Component side

IV-C) Fast Charge-Sensitive Preamplifier
Fig. 26 shows the schematic and Fig. 27 the layout of a faster (rise-time $\simeq 8$ nsec.) charge-sensitive amplifier (gain $\simeq 13000 \mathrm{e}^{-} / \mathrm{mV}$ ). This circuit is not currently in use, but is nonetheless quite handy. One must again watch the FET connections (as above), since our prints at ETH seem to be reversed.....

Figure 26


## Figure 27



Component side


Back side

